## EMV ccTalk electronic vending motors

## Operator's manual

## Rev. 1.02



The Alberici vending motors have been designed for dispensing packed products.

## EP-1P0C TRAS-101P CCTALK



EP-1A0C TRAS-101A CCTALK


EP-1LOC TRAS-101L CCTALK


## Sensore prodotto posteriore Rear sensor

Per impilatore prodotti allineato col retro del trascinatore o per confezioni voluminose
For products stacker aligned with the dispenser rear side or for large package size

## Sensore prodotto anteriore Front sensor

Per impilatore prodotti non allineato col retro del trascinatore
For products stacker non aligned with the dispenser rear side

## Sensore prodotto anteriore Front sensor

Per prodotti di forma rotonda (es. lattine) o di piccole dimensioni For round-shaped products (i.e. cans) or for small packages

## DIMENSIONS

ニニニ＂L＂type activation lever
－The standard pad is equipped with a long tooth．Upon request，it can be supplied without tooth，or with a shorter one（half－length）

## 叟贯 <br> 12345678



8 Dip－Switch Row for ccTalk Address setting


## TECHNICAL DATA

Power supply
No load current
Max．efficiency current
Stall current
Operating Temperature
Operating Mode
$12-24 \mathrm{Vdc}$（automatic compensation）
30 mAmp
1 Amp（output power 12 W ）
0，550 Amp
$0-50^{\circ} \mathrm{C}$
Intermittent operation

## CONNECTORS

The Alberici vending motors can be provided either with 6 pin standard Pulse communication interface（TRAS－001P，TRAS－001A，TRAS－001L，TRAS－001D，TRAS－ 001C），or with 10pin ccTalk protocol communication interface（TRAS－101P，TRAS－ 101A，TRAS－101L）．The pin－out for the ccTalk version is as follows：

## CCTALK



## PUSHBUTTON



## GENERAL INFORMATION

An 8-elements Dip-Switch Row is located on the side of the dispenser. Such DS Row allows to set the address of each dispenser in the same machine system.

Binary combinations resulting in 0 (all DS to OFF), 1 (first DS to ON, all others to OFF), and 2 (second DS to ON, all others to OFF) are free and available for Manufacturers who might need to use custom-made product codes.
All other combinations produce the operating Addresses from 3 to 255.

When the DS are set to binary combination 0 (all DS to OFF), the board produces by default the Address 03 . Such Address can be changed by sending the 'Address change' instruction; by this procedure, the machine control board will be setting the address of each dispenser, according to the momentary needs.
If the DS is set to a combination such as 3 or higher, the 'Address change' command will not be accepted, and the dispenser shall reply Nacknowledged.

IMPORTANT: the device accepts commands for dispensing one product unit per time. If the command asks for more than one product unit, the device shall reply Nacknowledged.

Power supply must be within 12 Vdc e 24 Vdc . The dispenser contains a compensation circuit that controls and equalizes the measured voltage level. The device will not work when voltage is less than 10 Vdc or exceeding 30 Vdc .

The ccTalk dispenser can accomodate one RGB pushbutton (see PIN-OUT here beside).
By using the Header 238 command, the RGB lights can be controlled, or by the header 248 , check whether the pushbutton is being pressed.


Stand-by position of the product dyke: by default, the belt stops in such a position that the product dyke stands in the diagonal position (as in figures on page 1).
If the belt must stop its rotation in at a different point, such as to get the dyke in a more convenient position (for instance, to retain small size products), the Header 214 can be programmed accordingly (see page 11).



## 1. ccTalk commands

## 254 Simple Poll

Transmitted data: none
Received data: ACK
Simple polling, mostly used to check device at selected address.
253 Address Poll
Transmitted data: none
Received data: One byte (current device address).
This command is best to be sended with address 0 .
All slaves respond with only one byte - own address after (1200 - 4*device address) miliseconds.It is used to get all slave addresses in the network.

252 Address Clash
Transmitted data: none
Received data: One byte (current device address).
This command is best to be sended with address 0 .
All slaves respond with only one byte - own address after (1200 - 4* random(255)) miliseconds. It is used to find possible two devices with same addresses in the network.

251 Address change
Transmitted data: new address
Received data: ACK
Jumper JP1 must be closed before this operation and host must send this command with broadcast address (zero). If all was OK, eceived data is ACK with old address.New address is stored into NV memory and take effect at next command and every power up. Othervise answer is NACK. Operator can close/open jumper with power on.

246 Request manufacturer id
Transmitted data: none
Received data: "Alberici"
Received data is ASCII string with manufacturer ID ("Alberici").

## 245 Request equipment category ID

Transmitted data: none
Received data: "Pusher"
Received data is ASCII string with equipment category ID ("pusher").

## 244 Request product code

Transmitted data: none
Received data: $\quad$ "Motor Vending M1"
Received data is ASCII string with product code ("Motor Vending M1").

## 242 Request serial number

Transmitted data: none
Received data: three byte serial number
Received data is three byte serial number written in NV memory in order LSB - MSB.

## 241 Request software revision

Transmitted data: none
Received data: four byte
Received data is four byte ASCII string with software revision ("1.01" for example).

217 Request dispenser high/low status
Transmitted data: none
Received data: one byte
Received byte is dispenser hi/low status where:

| bit0 : | $1-$ empty <br> $0-$ not empty |
| :--- | :--- |
| bit1 : | $1-$ full |
| bit2 : | $0-$ not full |
| bit3 : | not used |
| bit 4: | now level sensor is on |
| bit5 : | hi level sensor is on |
| bit6 6 | not used |
| bit7 : | not used |

## 216 Request data storage available

Transmitted data: none
Received data: five bytes
Description:
byte 1 : memory type
byte 2 : read blocks
byte 3 : read bytes per block
byte 4 : write blocks
byte 5 : write bytes per blocks
In this moment no data storage is available, so result is 0000000000 .

## 192 Request build code

Transmitted data:
none
Received data: "AMV001"
Received data is ASCII string with build code ("ALM01v01" for example).
172 Emergency stop
Transmitted data: none
Received data: one byte
Device is momentarily stopped, and received data is number of products left for dispense.

## 169 Request address mode

Transmitted data: none
Received data: 0xB2
Description:

- Address is stored in NV memory (B2)

168 Request dispense count
Transmitted data: none
Received data: three bytes (first LSB, last MSB)
Total dispense counter saved in NV memory.
Data is transmitted from LSB to MSB byte.
167 Dispense products
Only quantity 1 (one piece) can be dispensed per each dispense command. If an attempt is made to dispense more than one product by a single dispense command, the motor dispenser responds with a "NACK" signal.
Transmitted data: four bytes
Received data: ACK or NACK
Host sends four bytes. First three is serial address of the motor, and fourth is number of products (1) to be dispensed.
Received data is ACK if everything is OK, or else NACK.
In both cases reasons for NACK can be:

- incorrect serial number
- Motor current overflow occurred during last dispense (see "Test dispenser")
- dispense is not enabled (see "Test dispenser")
- incorrect number of bytes was send from host to dispenser
- previous dispense operation is in progress.

166 Request dispenser status
Transmitted data: none
Received data: four bytes
Description:
byte 1 : event counter - number of good dispense events since last reset
byte 2 : number of goods to push out since last dispense command
(decrements with each good pushed).
byte 3 : number of goods pushed out since last dispense command (increments with each good pushed).
byte4 : number of goods failed to push out since last dispense command (this counter is cleared during pushout).

164 Enable dispenser
Transmitted data: one byte
Received data: ACK
Transmitted byte must be 0xA5.Only in that case dispense is enabled.
Next attempt to send this command without correct parameter disables the dispense.

## 163 Test dispenser

Transmitted data: none
Received data: one byte
Received bytes are:
byte 1 :
0 -
1 -
2 -
3 -
4 - Pushout timeout occurred (next pushout or reset clear this flag)
5 - Motor current overflow during last dispense (soft reset clear this flag or if motor is released or reset)
6 - Power up detected
(power up set and soft reset clear this flag)
7 - Dispense disabled
(power up set and 'Enable device' command with A5 parameter reset flag)
004 Request comms revision
Transmitted data: none
Received data: three bytes
Description:
byte1 : cctalk level
byte2: major revision
byte 3 : minor revision

## 001 Reset device

Transmitted data: none
Received data: ACK
NOTE: Device response time for this command is app. 150 ms .

## 2. Setting start position

If motor is not in start position, operator must:

- power off device
- close jumper J1
- power on device and wait until belt stops in start position
- power off
- open jumper J1
- power on for normal operation.


## 3. Pinout

1 cctalk data line
4,8 Ground
$7,10 \quad+24 v$
2,3,5,6,9 not connected

## Motor vending Command header set

List of cctalk command headers for Motor vending dispenser:

| Code |  | Command header | Note |
| ---: | :---: | :--- | :--- |
| 254 | FE | Simple poll | Return ACK |
| 253 | FD | Address poll | MDCES support in broadcast mode |
| 252 | FC | Address clash | MDCES support in broadcast mode |
| 251 | FB | Address change | support, non volatile |
| 248 | F8 | Request status | Return extern RGB switch information |
| 246 | F6 | Request manufacturer id | 'Alberici' |
| 245 | F5 | Request equipment category id | 'Dispenser' |
| 244 | F4 | Request product code | 'AD-MTV-1' <br> request |
| 242 | F2 | Request serial number | Return 3 byte: number from 0 to <br> 16.777.215 |
| 241 | F1 | Request software revision | 'rx.xx' <br> numbers |
| 238 | EE | Test outputs lines | Set external light on rgb switch |
| 236 | EC | Read optostates | Compatibility |
| 217 | D9 | Request dispense high/low stat. | Return empty/full status |
| 215 | D7 | Read data block | Return settting information |
| 214 | D6 | Write data block | Program setting information |
| 172 | AC | Emergency stop | Return ACK with one byte |
| 167 | A7 | Dispense Slave products | Data = Serial number +( byte=1 ) |
| 166 | A6 | Request Slave status | Return dispensed product counters |
| 164 | A4 | Enable Slave | Data must be A5 |
| 163 | A3 | Test Slave | Return hardware status |
| 1 | 1 | Reset device | Software reset |

## Setting the Slave Address via Hardware

The default address of the Alberici motor vending dispenser can be changed via the on-board 8 dip switch row.
See below the various combinations, each of them relating to one particular address.
Slave Address Table (empty box stands for 'Off' position of the Dip-Switch):

| DipSw8 | DipSw7 | DipSw6 | DipSw5 | DipSw4 | DipSw3 | DipSw2 | DipSw1 | Address |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  | By default=03 |
|  |  |  |  |  |  |  | On | By default=03 |
|  |  |  |  |  |  | On |  | By default=03 |
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